

An introduction to geophysical fluid dynamics

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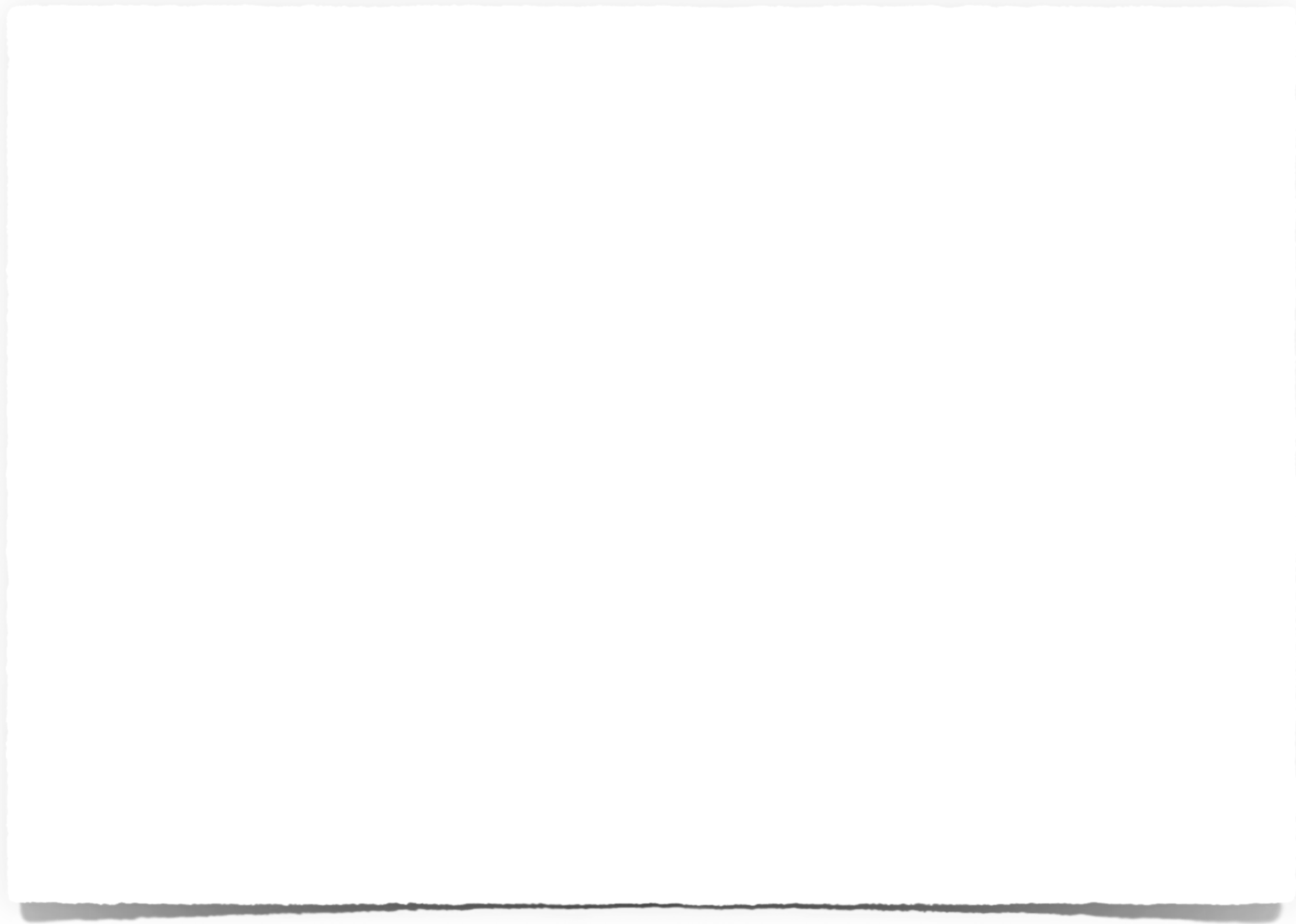
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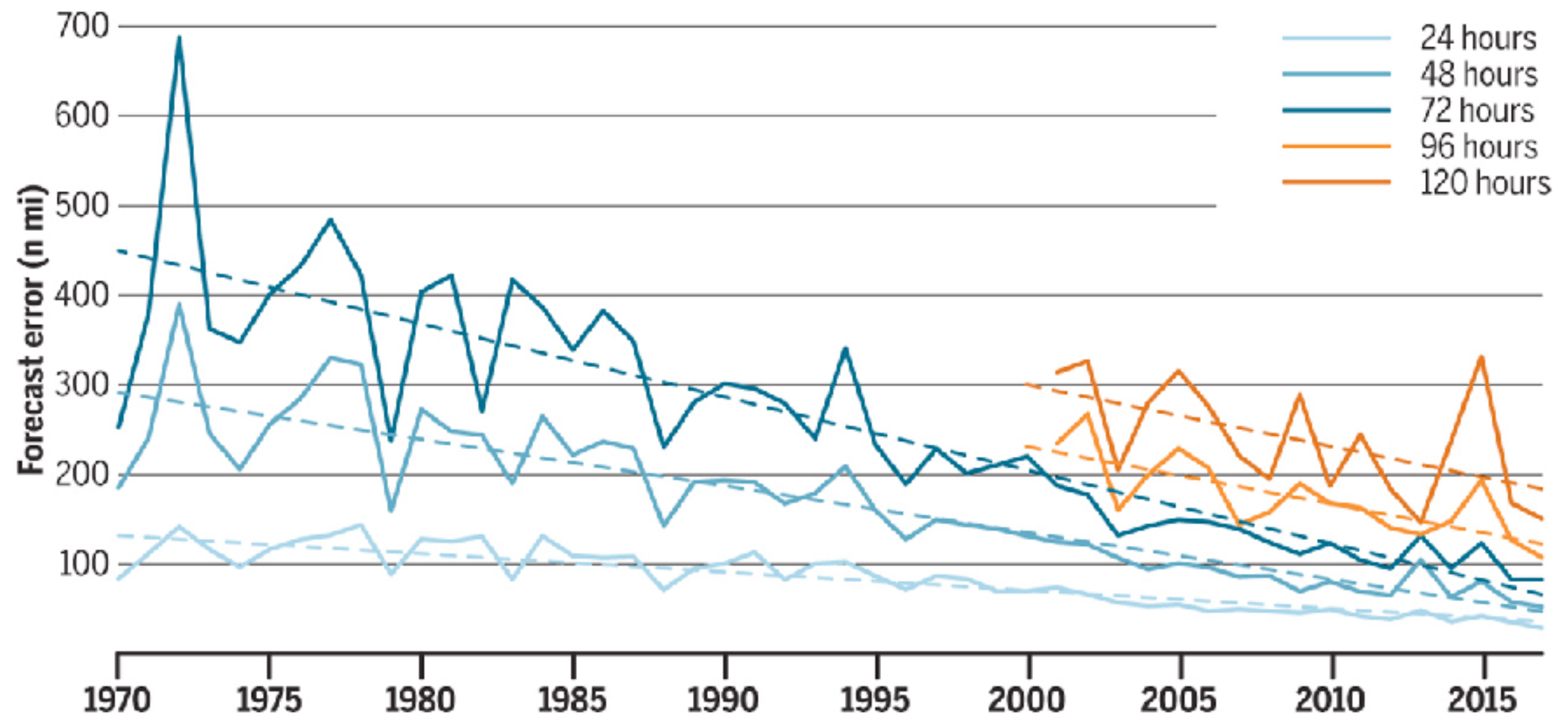






Advances in hurricane prediction

Data from the NOAA National Hurricane Center (NHC) (13) show that forecast errors for tropical storms and hurricanes in the Atlantic basin have fallen rapidly in recent decades. The graph shows the forecast error in nautical miles (1 n mi = 1.852 km) for a range of time intervals.



Alley et al., Science (2019)

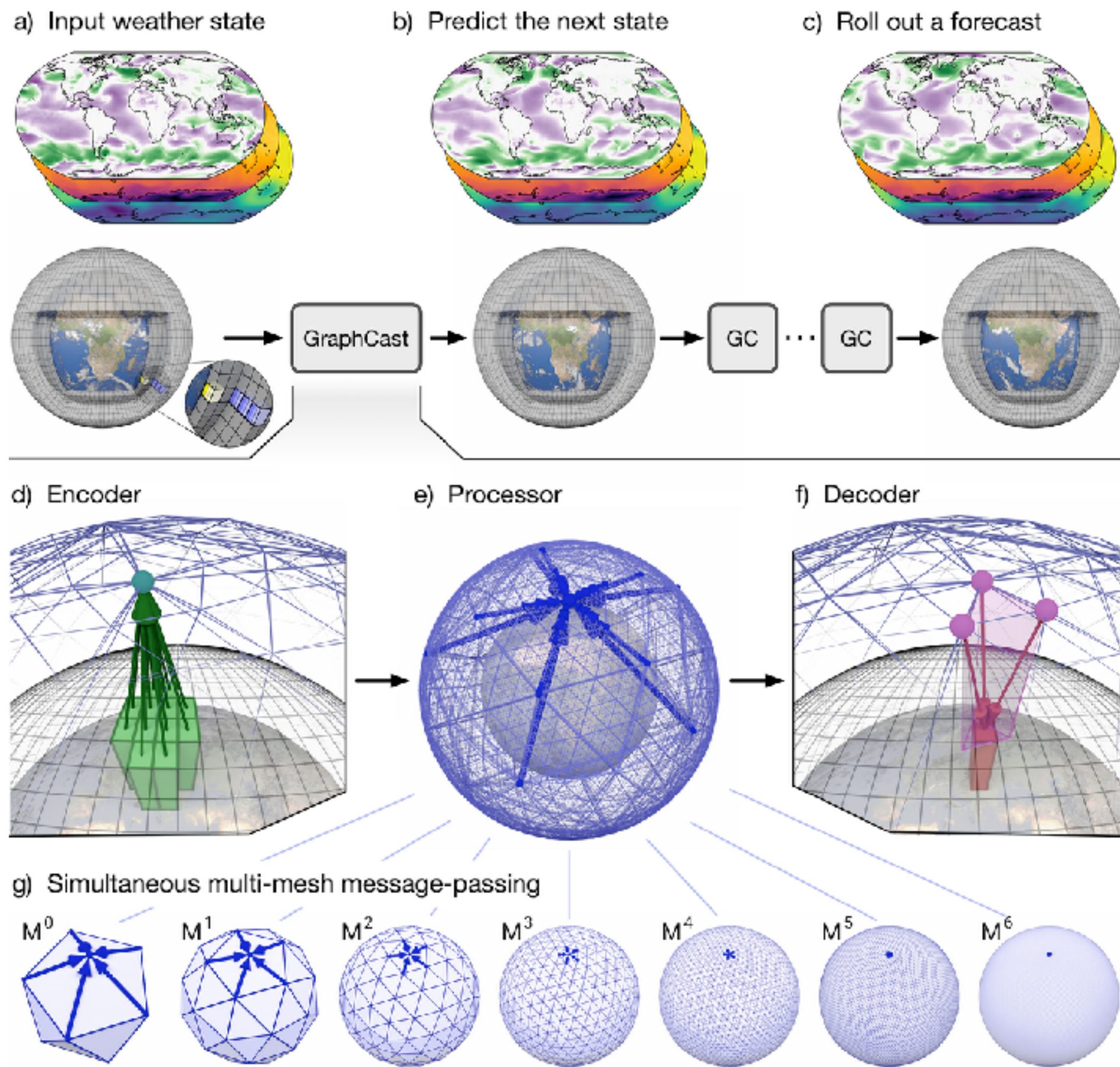
Basic physical processes $\rightarrow$ formal models

forecast $\leftarrow$ simplification $\leftarrow$

NN? Models
vs. data?

Or models + data

Physics $\rightarrow$ Conservation laws
 $\rightarrow$ Forces
 $\rightarrow$ Geometry and B.C.



Lam et al., Science (2023)

The fundamental equations

$$\left\{ \begin{array}{l} \frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \underline{u}) = 0 \\ \frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} = -\frac{1}{\rho} \nabla p + \nu \nabla^2 \underline{u} + \left(\frac{\nu}{3} + \nu' \right) \nabla (\nabla \cdot \underline{u}) + \frac{\underline{f}}{\rho} \\ \frac{\partial \theta}{\partial t} + \underline{u} \cdot \nabla \theta = S' \end{array} \right.$$

Mass conservation



$$\frac{\partial}{\partial t} \int \rho dV = - \int \rho \underline{u} \cdot d\underline{S} = - \int \underline{\nabla} \cdot (\rho \underline{u}) dV$$

$$\Rightarrow \boxed{\frac{\partial \rho}{\partial t} + \underline{\nabla} \cdot (\rho \underline{u}) = 0}$$

Then the conservation of mass is

$$\boxed{\frac{D\rho}{Dt} + \rho \nabla \cdot \underline{u} = 0}$$

and in an incompressible fluid

$$\boxed{\nabla \cdot \underline{u} = 0}$$

Example: Ideal gas in the atmosphere

$$P = \rho R T$$

Atmospheric pressure $\approx 10^5 \text{ Pa}$

δP from meteorological phenomena $\approx 10^3 \text{ Pa}$

Sound waves (60 dB) $\approx 10 \text{ Pa}$

Conservation of momentum

$$\rho \frac{D\mathbf{u}}{Dt} = \mathbf{F}$$

$$\rho \left(\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} \right) = \mathbf{F}$$

pressure gradients
viscosity
gravity
rotation
external forces

Energy

$$\frac{Ds}{Dt} = 0$$

If we have sources (e.g., latent heat)

$$\frac{\partial s}{\partial t} + \mathbf{u} \cdot \nabla s = S$$

For an ideal gas

$$S = C_p \ln T - Nk \ln P + S_0$$

$$= C_p \ln \left(\frac{T}{P^K} \right) + S_0 \quad \text{with } K = \frac{Nk}{C_p}$$

If fluid elements are adiabatic $dS = 0 = C_p \frac{dT}{T} - Nk \frac{dP}{P}$

$$C_p \ln \left(\frac{\Theta}{T} \right) = Nk \ln \left(\frac{P_0}{P} \right)$$

$$\Rightarrow \boxed{\Theta = T \left(\frac{P_0}{P} \right)^K}$$

Potential
temperature

Using

$$S = C_p \ln \Theta + S_1$$

$$\Rightarrow \boxed{\frac{\partial \Theta}{\partial t} + \underline{v} \cdot \underline{\nabla} \Theta = S'}$$

Vorticity

$$\underline{\omega} = \underline{\nabla} \times \underline{u}$$

for an incompressible flow (but ρ may not be constant)

$$\underline{\nabla} \times \frac{\partial \underline{u}}{\partial t} = \frac{\partial \underline{\omega}}{\partial t} = -\underline{\nabla} \times (\underline{u} \cdot \underline{\nabla} \underline{u}) - \underline{\nabla} \times \left(\frac{1}{\rho} \underline{\nabla} p \right) + \underline{\nabla} \times (\nu \nabla^2 \underline{u}) + \underline{\nabla} \times \left(\frac{f}{\rho} \right)$$

Using

$$\left\{ \begin{array}{l} \underline{u} \cdot \underline{\nabla} \underline{u} = -\underline{u} \times \underline{\omega} + \nabla^2 \left(\frac{u^2}{2} \right) \\ \underline{\nabla} \times (\underline{u} \times \underline{\omega}) = -\underline{\omega} (\underline{\nabla} \cdot \underline{u}) + (\underline{\omega} \cdot \underline{\nabla}) \underline{u} - (\underline{u} \cdot \underline{\nabla}) \underline{\omega} \\ \underline{\nabla} \times \left(\frac{1}{\rho} \underline{\nabla} p \right) = -\frac{1}{\rho^2} \underline{\nabla} \rho \times \underline{\nabla} p \end{array} \right.$$

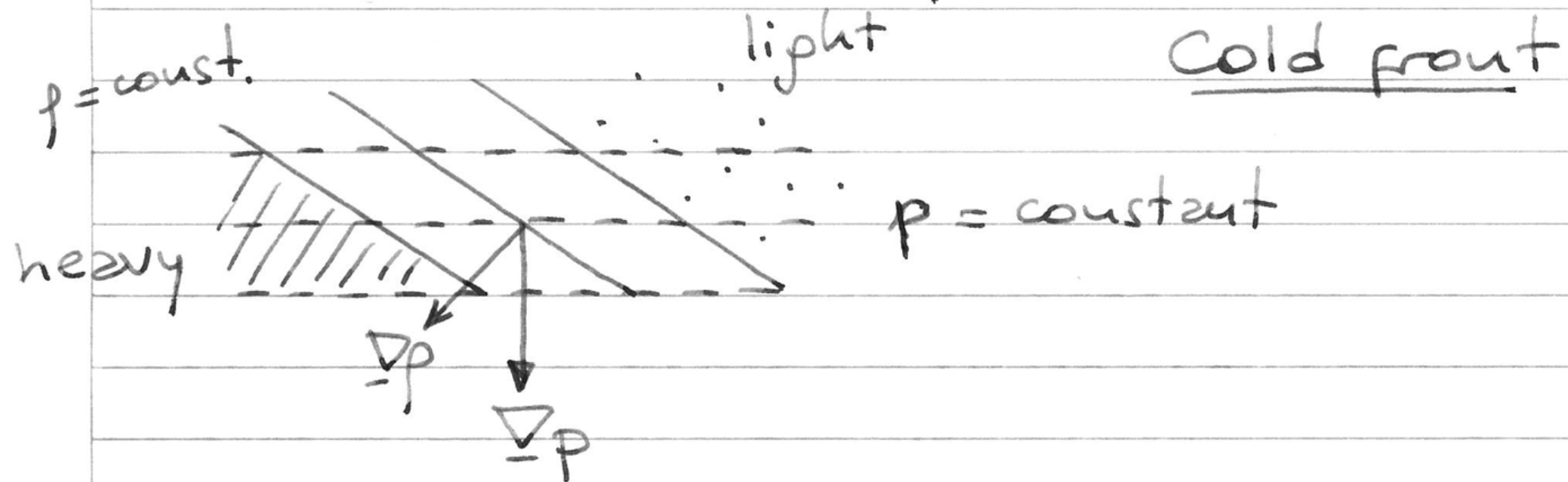
$\frac{D\underline{\omega}}{Dt}$	baroclinic term
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$$\Rightarrow \frac{\partial \underline{\omega}}{\partial t} + \underline{u} \cdot \nabla \underline{\omega} = \underline{\omega} \cdot \nabla \underline{u} + \frac{1}{\rho^2} \nabla \rho \times \nabla p$$

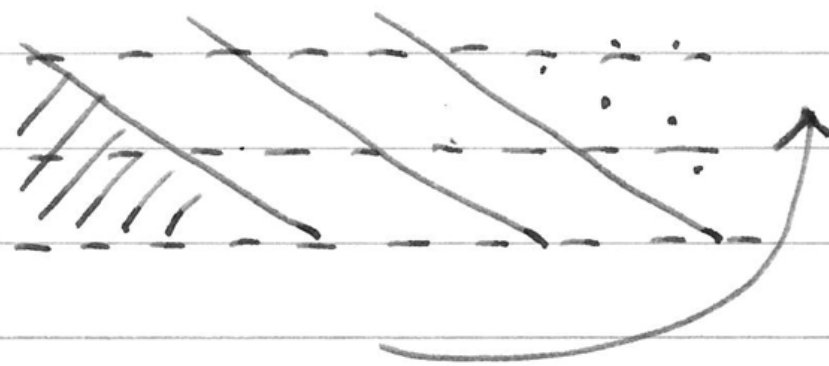
$$+ \nabla \times (\nu \nabla^2 \underline{u}) + \nabla \times \left(\frac{\underline{f}}{\rho} \right)$$

If the flow is barotropic, $\rho = \rho(p) \Rightarrow \nabla \rho \times \nabla p = 0$

Example: generation of circulation by baroclinicity



Light and heavy fluid feel the same force ($-\nabla p$), but light fluid moves upwards faster generating circulation



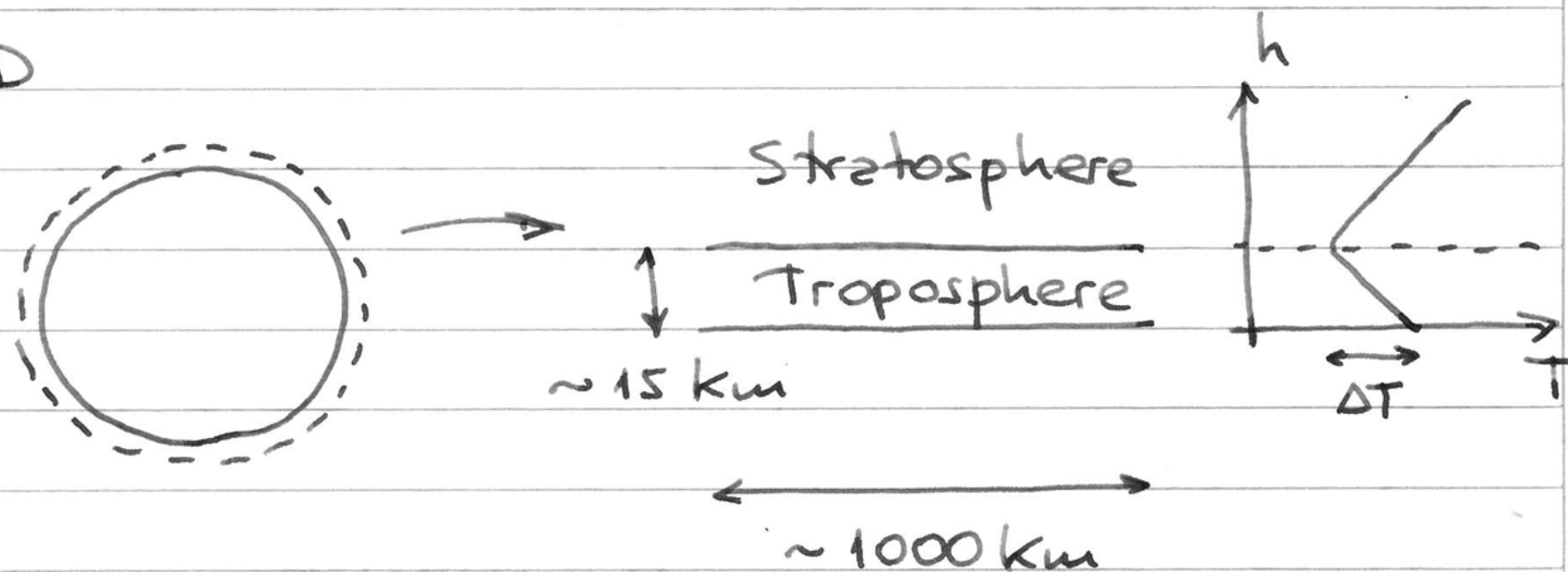
$\nabla \rho$ and ∇p
try to slip!

If $\rho = \text{const.}$ ($V = \text{const.}$) and f conservative

$$\Rightarrow \boxed{\frac{D\underline{\omega}}{Dt} = \underbrace{\underline{\omega} \cdot \nabla \underline{v}}_{\text{vortex stretching}} + V \nabla^2 \underline{\omega}}$$

vortex stretching

In 2D

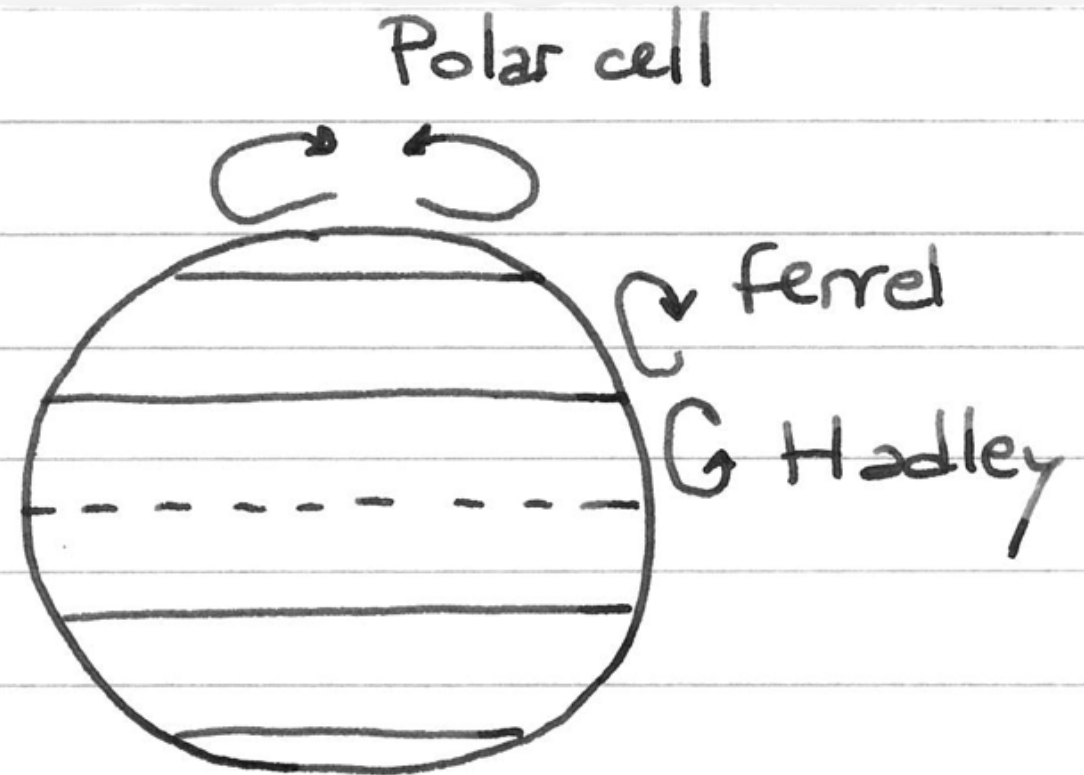
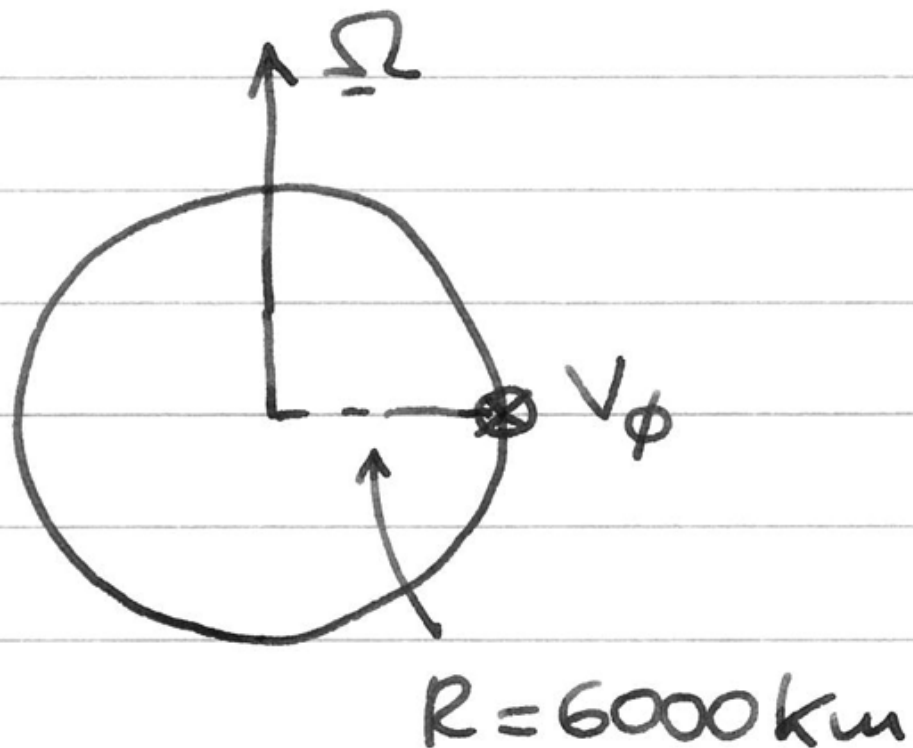


$$\underline{v} = (v_x, v_y, 0) = \underline{v}(x, y)$$

$$\underline{\omega} = \nabla \times \underline{v} = \omega \hat{z}$$

$$\Rightarrow \boxed{\frac{D\underline{\omega}}{Dt} = V \nabla^2 \underline{\omega}}$$

Rotating flows



$$T = \frac{2\pi}{\Omega} = 24 \text{ h}$$

$$V_\phi = \Omega R \approx 1600 \text{ km/h}$$

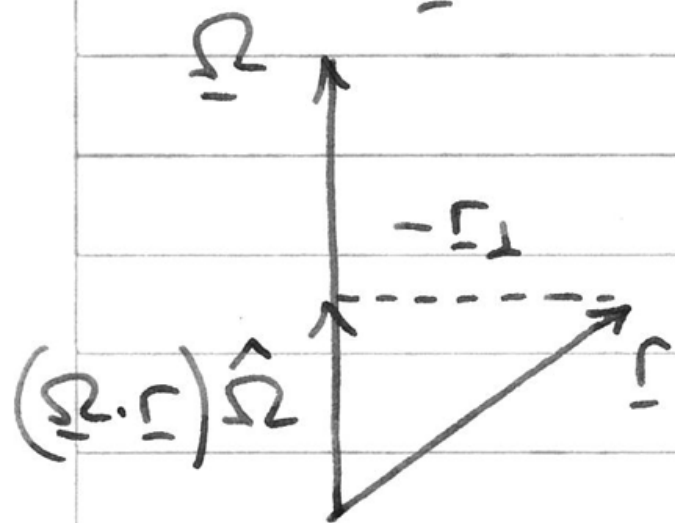
Atmospheric phenomena has $v \lesssim 200 \text{ km/h}$
(jet currents)

⇒ It makes sense to work in the rotating frame!

$$\rho \left(\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} \right) = \overset{\text{Coriolis}}{-\rho 2 \underline{\Omega} \times \underline{u}} - \overset{\text{centrifugal force}}{-\rho \underline{\Omega} \times (\underline{\Omega} \times \underline{r})} - \nabla p + \mu \nabla^2 \underline{u} + \underline{f}$$

The centrifugal force can be absorbed into $\underline{f}$ or p :

$$\begin{aligned} \underline{\Omega} \times (\underline{\Omega} \times \underline{r}) &= (\underline{\Omega} \cdot \underline{r}) \underline{\Omega} - \Omega^2 \underline{r} = \\ &= \Omega^2 [(\hat{\Omega} \cdot \underline{r}) \hat{\Omega} - \underline{r}] = -\Omega^2 \underline{r}_\perp \\ \Rightarrow -\underline{\Omega} \times (\underline{\Omega} \times \underline{r}) &= \Omega^2 \underline{r}_\perp = -\nabla \varphi_{ce} \end{aligned}$$



with $\varphi_{ce} = -\frac{\Omega r_\perp^2}{2}$

$$\Rightarrow \boxed{\frac{D\underline{v}}{Dt} = -2\underline{\Omega} \times \underline{v} - \frac{1}{\rho} \underline{\nabla} p + \underline{v} \underline{\nabla}^2 \underline{v} + \frac{f}{\rho} - \underline{\nabla} \phi_{ce}}$$

It corrects the
effective gravity

In the Earth the correction is $\mathcal{O}(10^{-3})$

Dimensionless numbers

Taking

$$\frac{|\underline{v} \cdot \nabla \underline{v}|}{|\nu \nabla^2 \underline{v}|} \sim \frac{U^2}{L} \cdot \frac{L^2}{\nu} \sim \boxed{\frac{UL}{\nu} = Re}$$

$$\frac{|\underline{v} \cdot \nabla \underline{v}|}{|2\Omega \times \underline{v}|} \sim \frac{U^2}{L} \cdot \frac{1}{2\Omega U} \sim \boxed{\frac{U}{2L\Omega} = Ro}$$

In the Earth ($L \sim 100 - 1000 \text{ km}$) $Ro \approx 0.1$

In Jupiter red spot $Ro \approx 0.015$

Taylor - Proudman theorem

$$\underline{v} = \underline{f} = 0, \text{ using } \underline{v} \cdot \underline{\nabla} \underline{v} = -\underline{v} \times \underline{\omega} + \nabla^2 \left(\frac{v^2}{2} \right)$$

$$\Rightarrow \frac{\partial \underline{v}}{\partial t} + \left(\underline{\omega} + 2\underline{\Omega} \right) \times \underline{v} = -\frac{1}{\rho} \underline{\nabla} p$$

Taking the curl and using

$$\underline{\nabla} \times (\underline{\omega} \times \underline{v}) = \underline{\omega} \underline{\nabla} \cdot \underline{v} - (\underline{\omega} \cdot \underline{\nabla}) \underline{v} + (\underline{v} \cdot \underline{\nabla}) \underline{\omega}$$

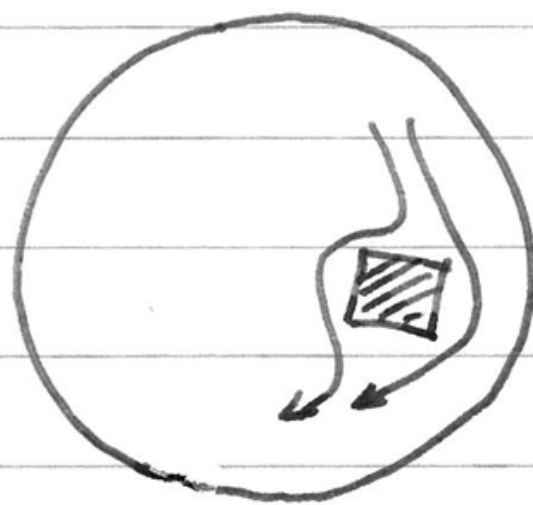
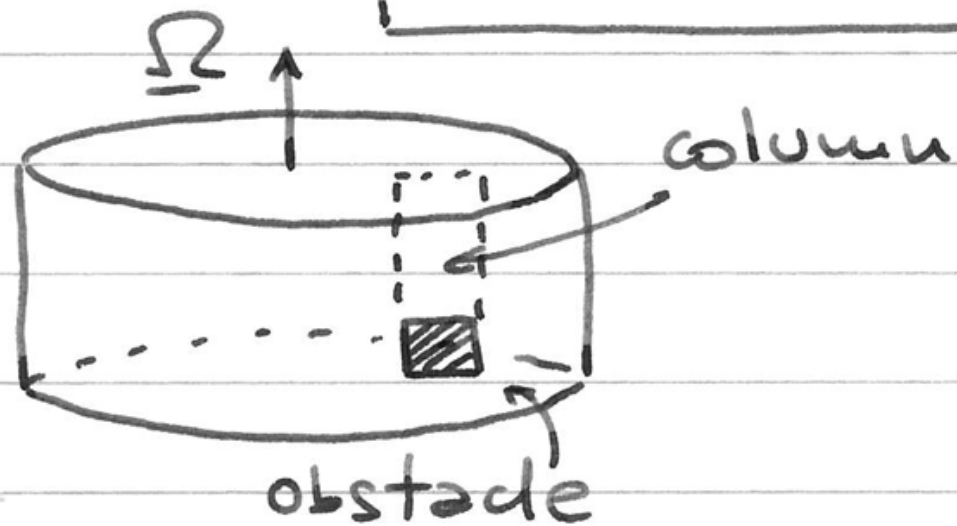
$$\Rightarrow \frac{D \underline{\omega}}{Dt} = (\underline{\omega} \cdot \underline{\nabla}) \underline{v} - \frac{1}{\rho^2} \underline{\nabla} \rho \times \underline{\nabla} p$$

Let's consider a barotropic stationary flow
with $R_0 \ll 1 \Rightarrow |\underline{\omega}| \ll |\underline{\Omega}|$ and $\underline{\omega}_0 \approx 2\underline{\Omega}$

$$\Rightarrow (2\underline{\Omega} \cdot \underline{\nabla}) \underline{v} = 0$$

For $\underline{\Omega} = \Omega \hat{z}$
 $\underline{v} = (u, v, w) \Rightarrow \begin{cases} 2\Omega \partial_z u = 0 \\ 2\Omega \partial_z v = 0 \\ 2\Omega \partial_z w = 0 \end{cases}$

$$\Rightarrow \underline{v} = \underline{v}(x, y)$$



blocking!

Record Player Fluid Dynamics: A Taylor Column Experiment



Rotation Rate:
33 RPM +1.5%

Top View



**Non-Rotating
Experiment**

Camera: Tank Frame

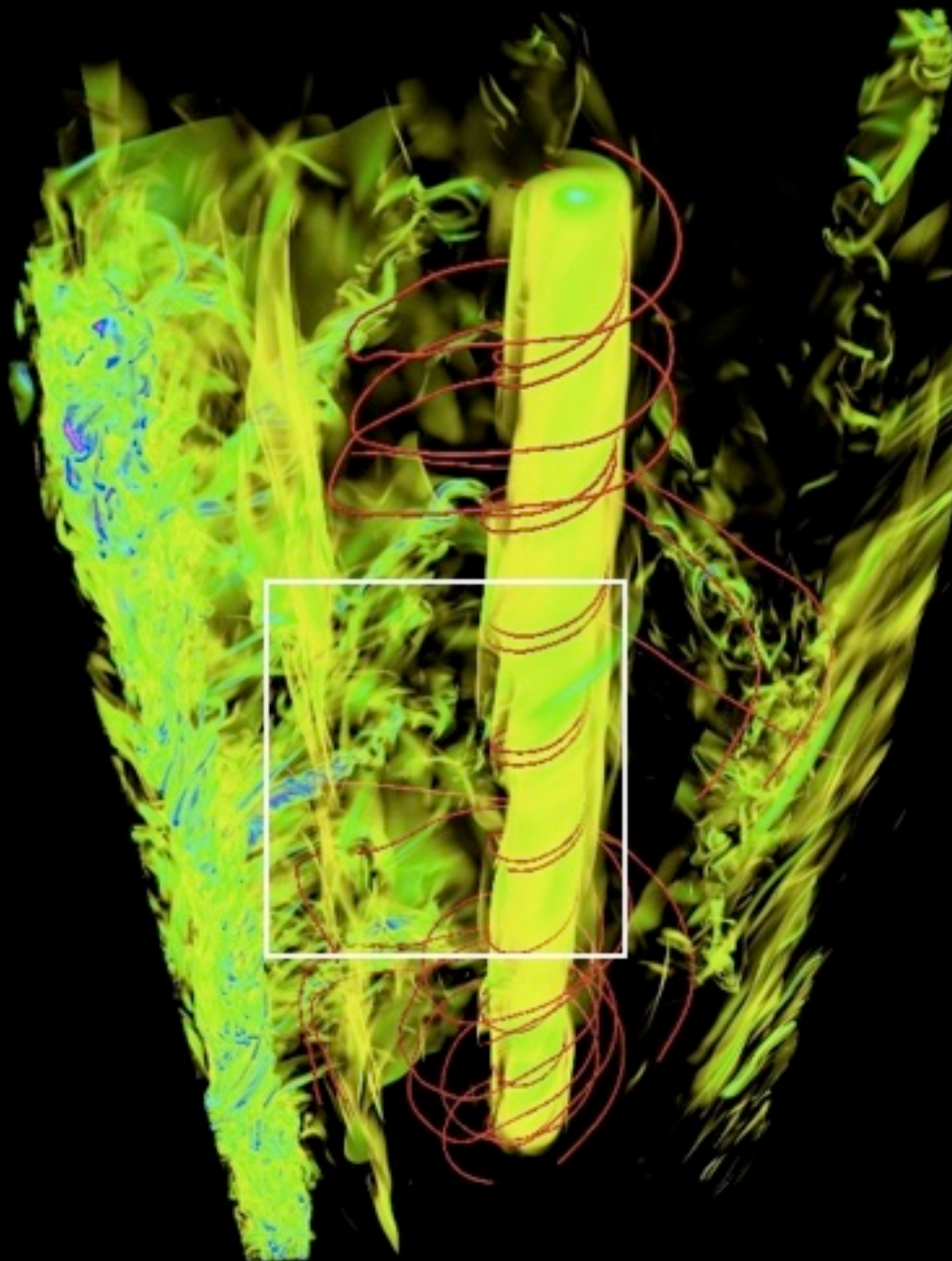
Side View



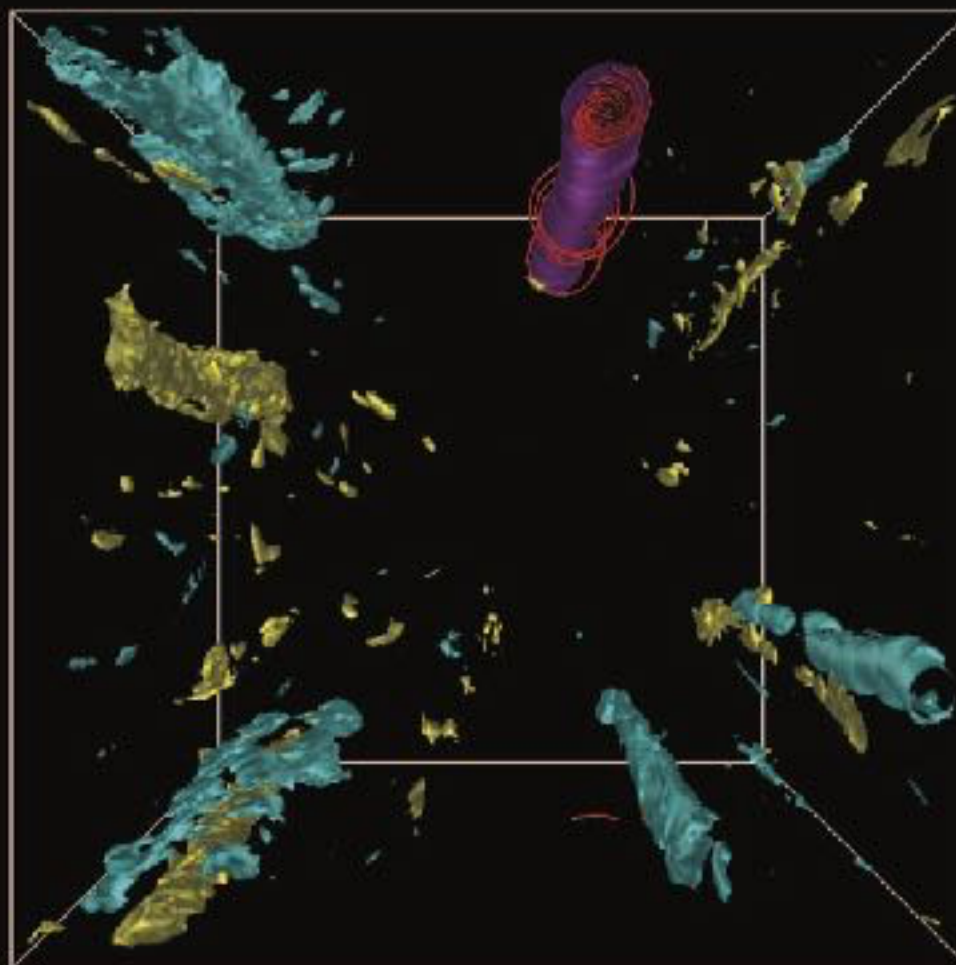
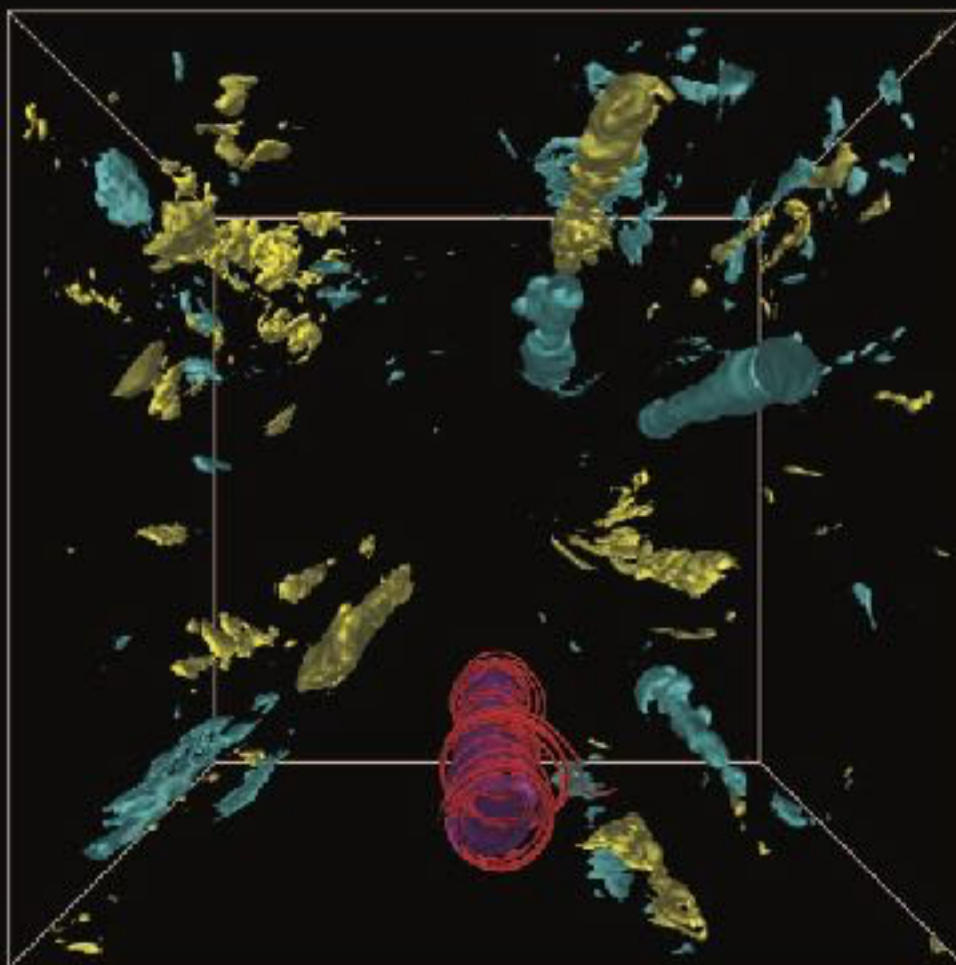
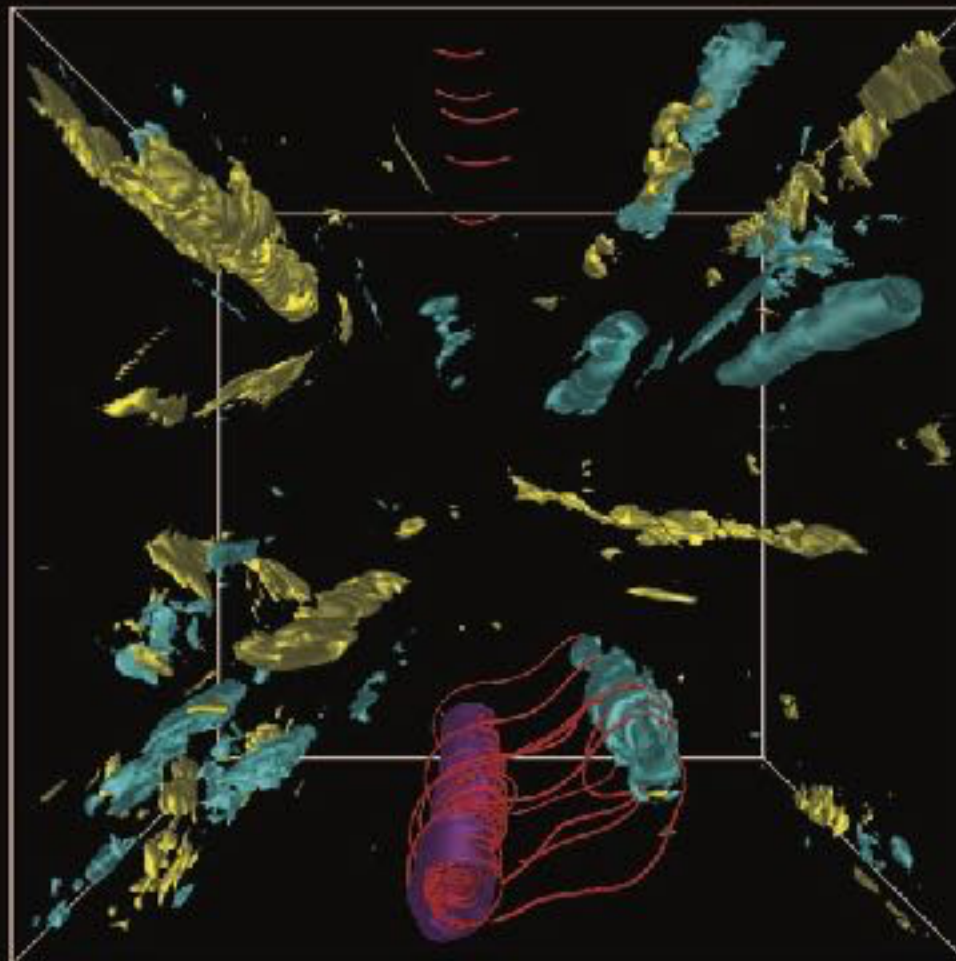
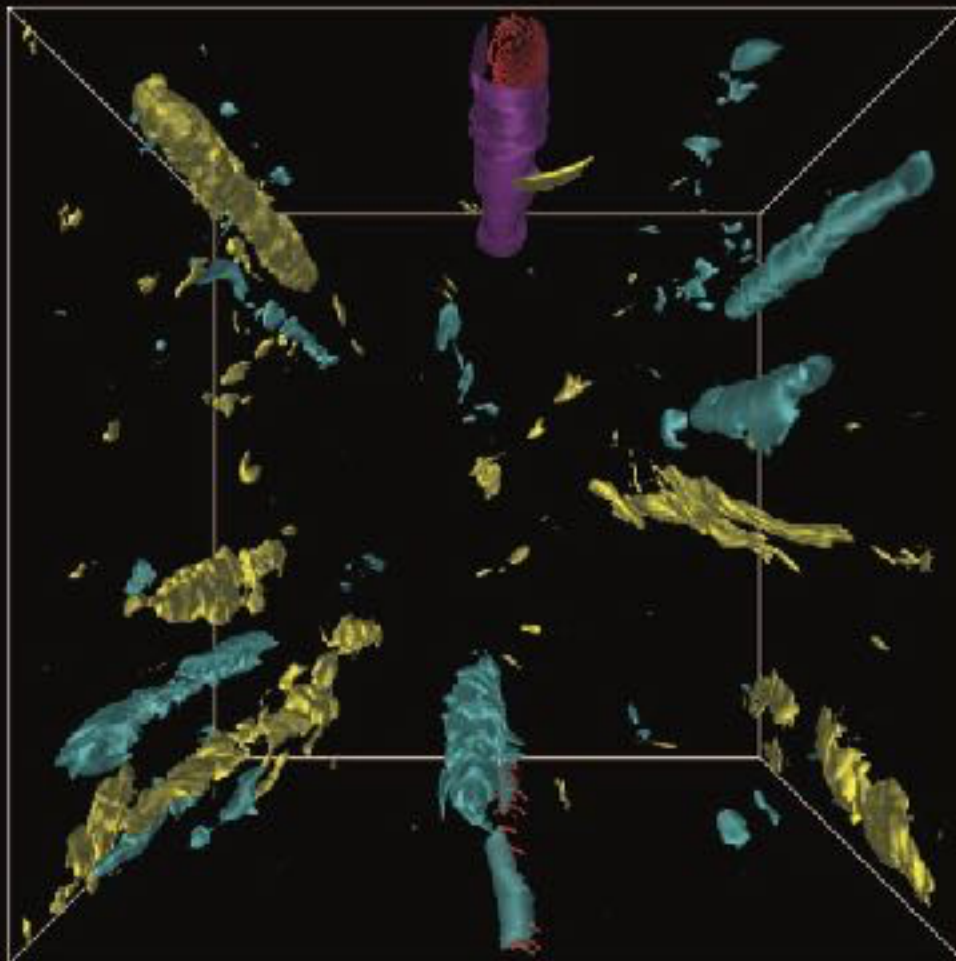
spinlabucla
SIMULATED BY DIGITAL INTERIORS LLC

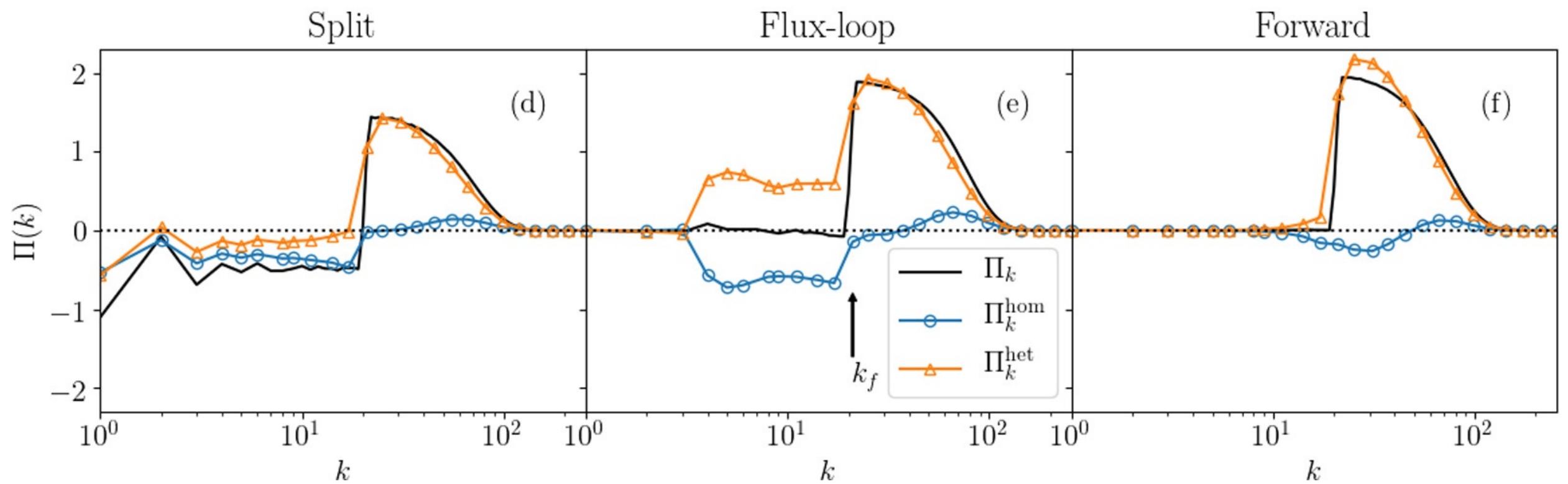
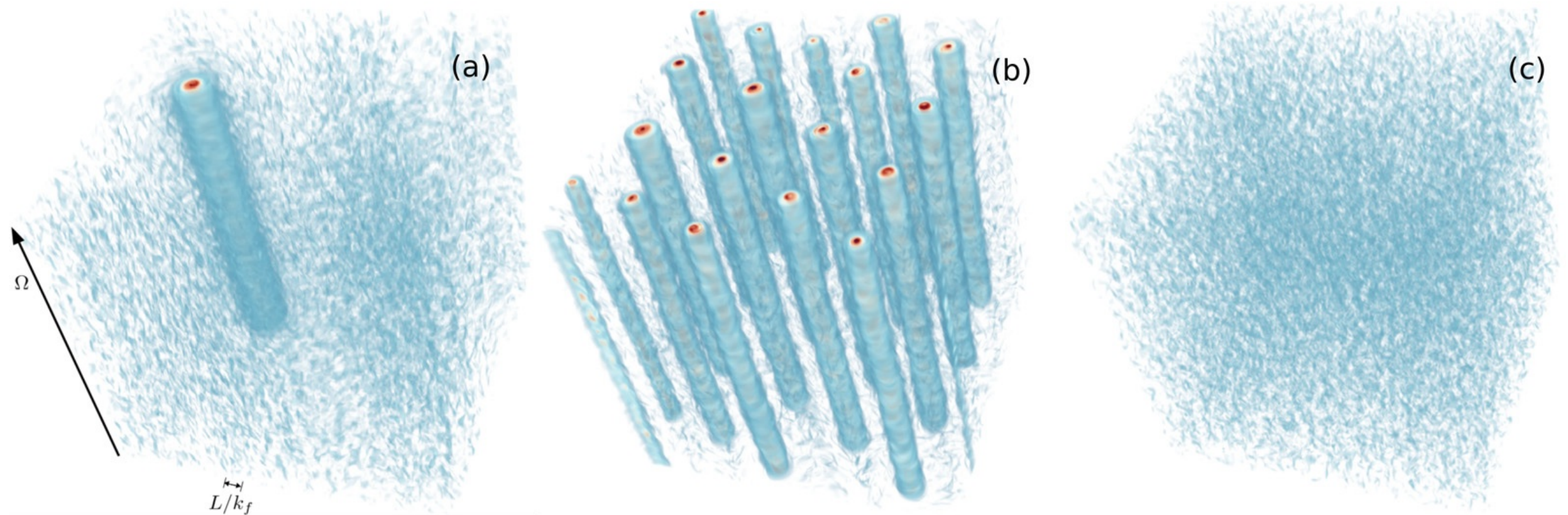
Sped Up 2x

<https://www.youtube.com/watch?v=7GGfsW7gOLI>



Mininni et al., JFM (2012)

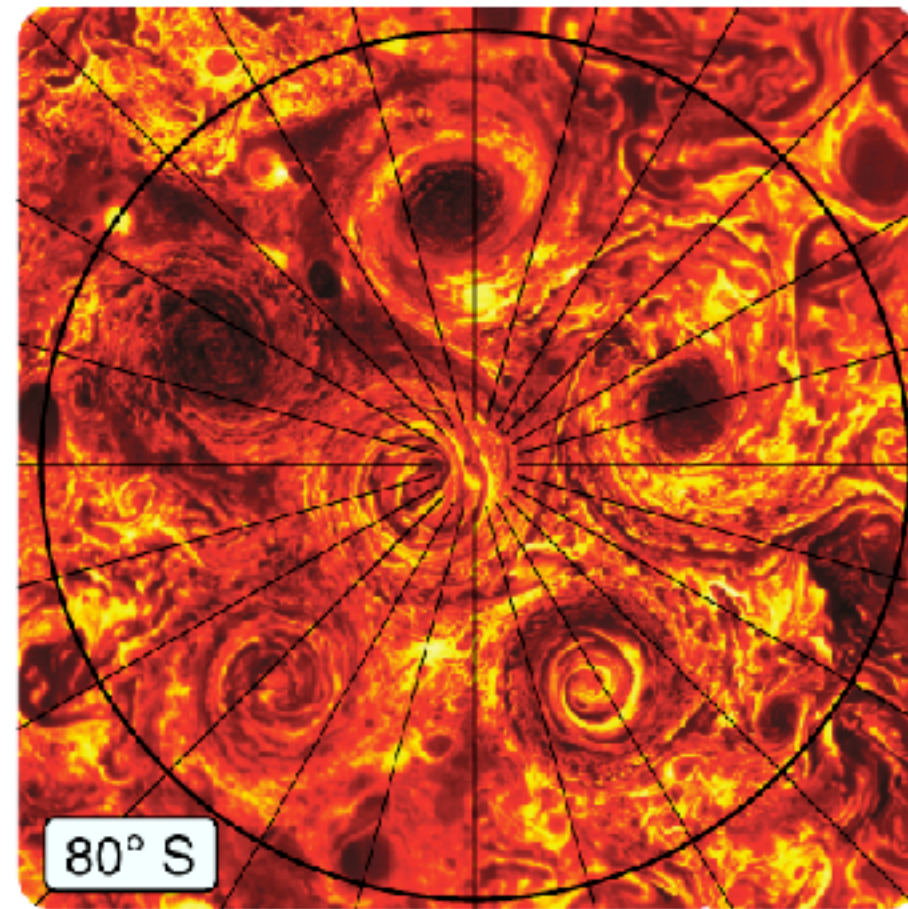
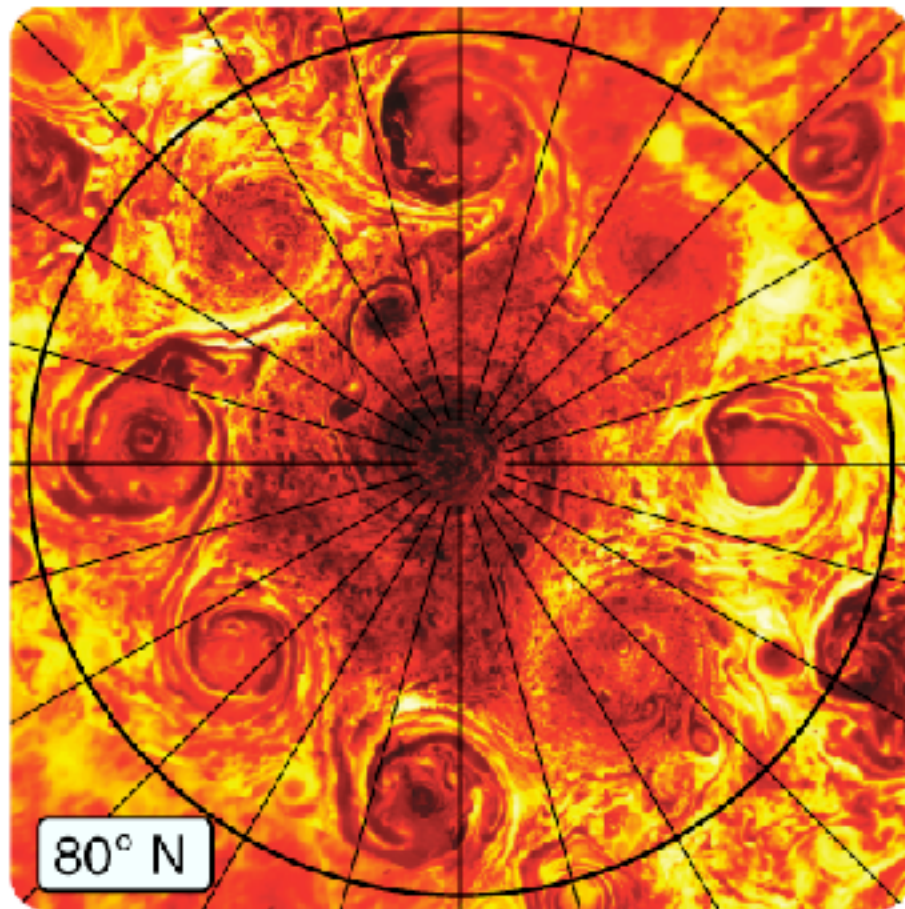




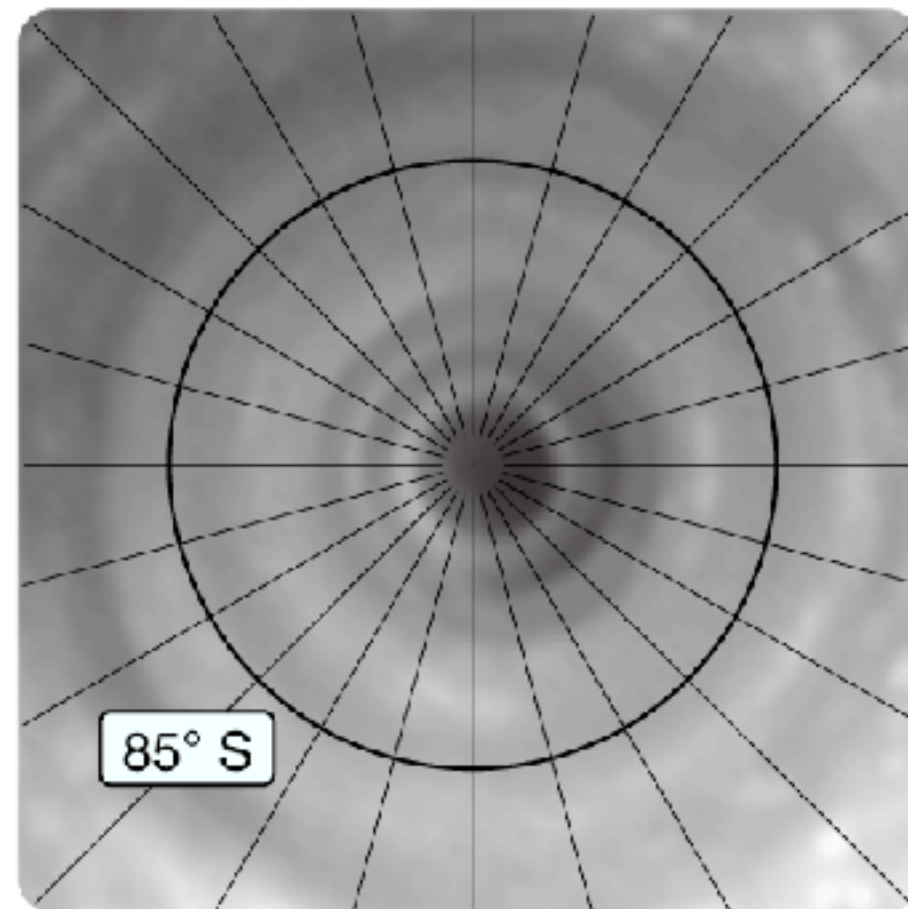
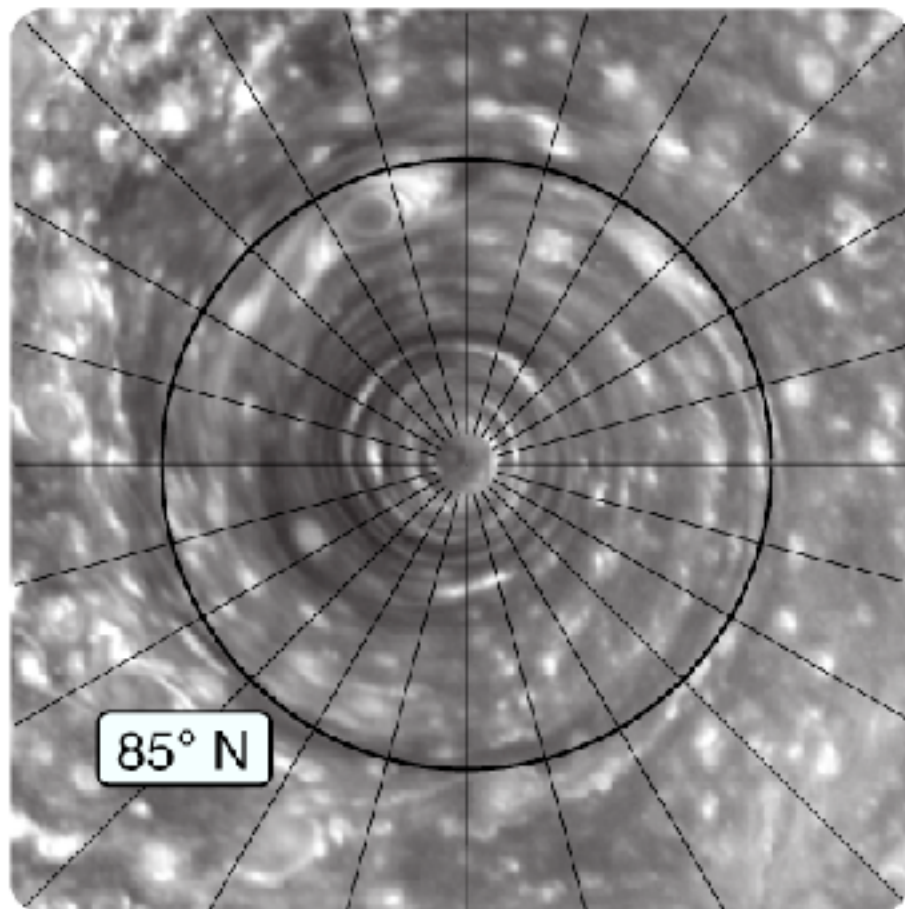
North pole

South pole

Jupiter



Saturn



Siegelman et al., Nat. Physics 2022)

Inertial waves

Let's consider $V = f = 0$, $R_0 \ll 1$, barotropic flow

$$\Rightarrow \frac{\partial \underline{\omega}}{\partial t} + \underline{v} \cdot \underline{\nabla} \underline{\omega} = \underline{\omega}_a + \underline{\nabla} \underline{v}$$

Linearizing for $|\underline{\omega}|, |\underline{v}| \ll 1$

$$\frac{\partial \underline{\omega}}{\partial t} = 2 \underline{\Omega} \cdot \underline{\nabla} \underline{v}$$

Taking $\underline{\nabla} \times \frac{\partial}{\partial t}$, and using $\underline{\nabla} \times \underline{\nabla} \times \underline{v} = -\underline{\nabla}^2 \underline{v} + \underline{\nabla}(\underline{\nabla} \cdot \underline{v})$

$$\Rightarrow \boxed{\frac{\partial^2}{\partial t^2} (\underline{\nabla}^2 \underline{v}) + 4 (\underline{\Omega} \cdot \underline{\nabla})^2 \underline{v} = 0}$$

It looks like a wave equation.

We look for solutions

$$\underline{v} = \underline{v}_0 e^{i(\underline{k} \cdot \underline{x} - \sigma t)}$$

$$\Rightarrow \sigma^2 k^2 - 4(\underline{\Omega} \cdot \underline{k})^2 = 0$$

$$\Rightarrow \boxed{\sigma(\underline{k}) = \pm 2 \frac{\underline{\Omega} \cdot \underline{k}}{k}}$$

Dispersion
relation

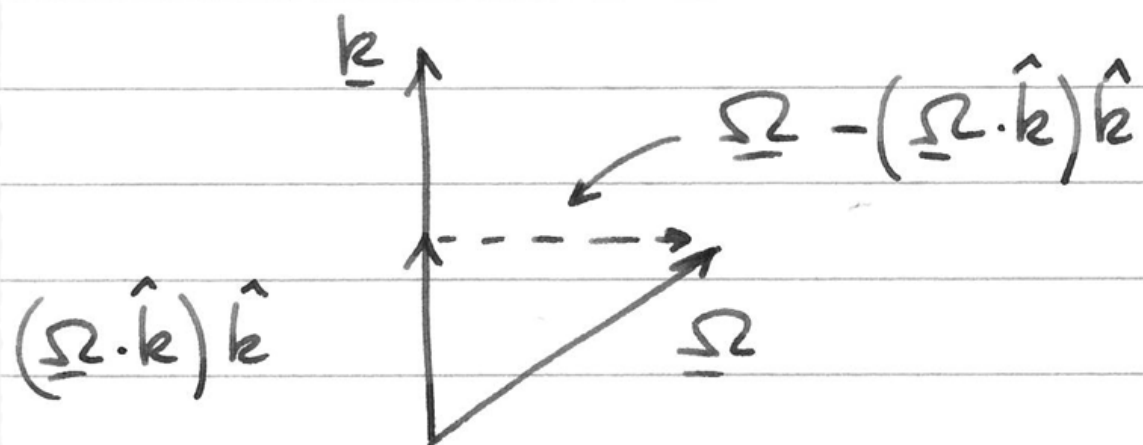
Phase velocity $\underline{c}_p = \frac{\sigma}{k^2} \underline{k} = \pm 2 \frac{(\underline{\Omega} \cdot \underline{k})}{k^3} \underline{k}$

← wave
propagation

Group velocity:

$$\underline{c}_g = \underline{\nabla}_k \sigma = \pm 2 \frac{k^2 \underline{\Omega} - (\underline{\Omega} \cdot \underline{k}) \underline{k}}{k^3}$$

← energy
propagation



Note that

$$\underline{c}_g \perp \underline{k} \parallel \underline{c}_p$$

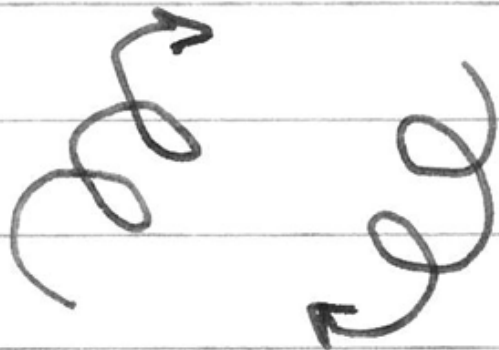
Besides $\underline{\omega} = \underline{\nabla} \times \underline{u} = i \underline{k} \times \underline{u}_0 e^{i(\underline{k} \cdot \underline{x} - \sigma t)}$

And $\frac{\partial \underline{\omega}}{\partial t} = -i\sigma \underline{\omega} = i 2 (\underline{\Omega} \cdot \underline{k}) \underline{u}$

$$\Rightarrow \underline{\omega} = \pm k \underline{u}$$

or $i \hat{k} \times \underline{u}_0 = \pm \underline{u}_0$

and the waves are circularly polarized
(helical)



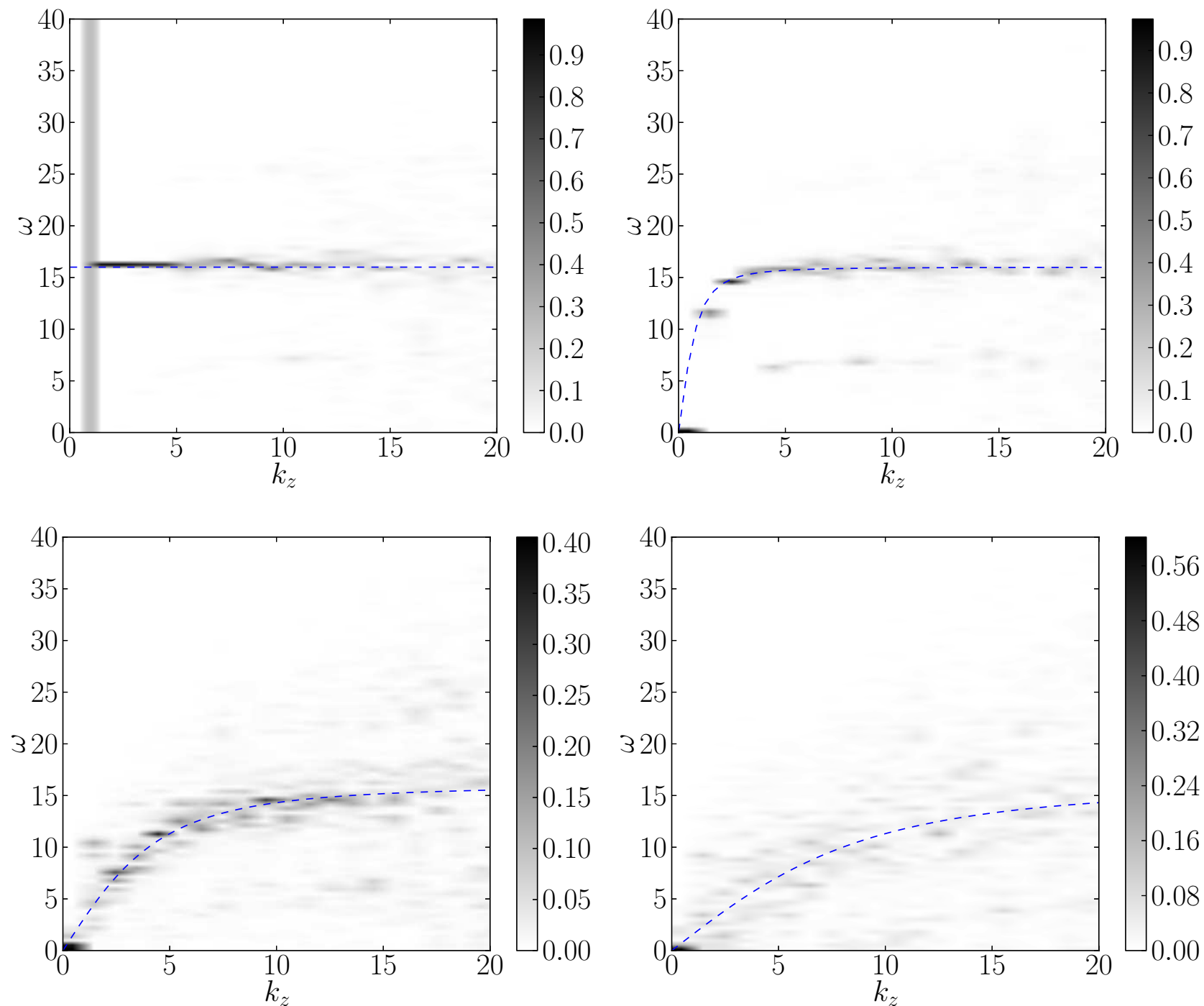
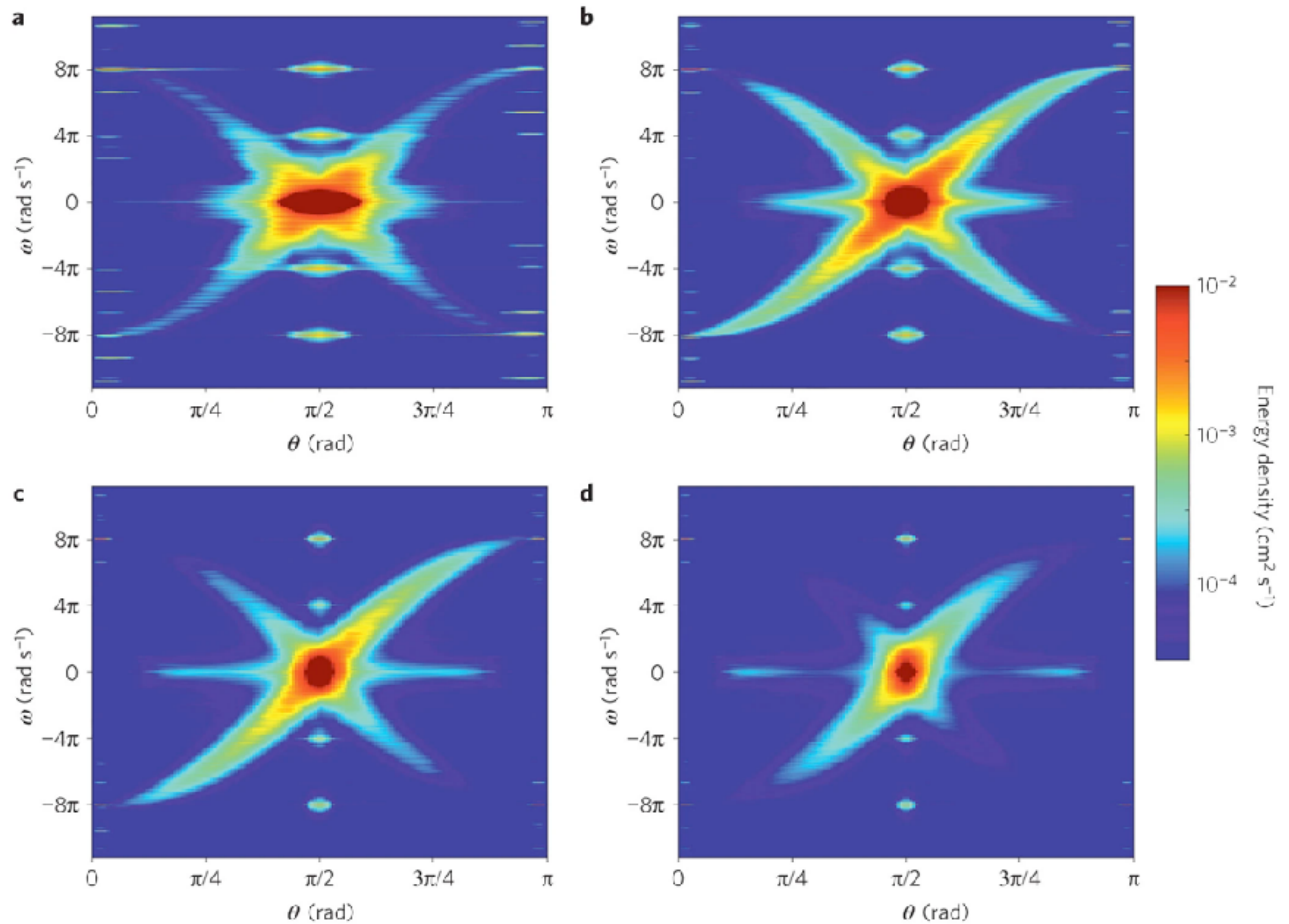


FIG. 3. Normalized wave vector and frequency spectrum $E_{11}(\mathbf{k}, \omega)/E_{11}(\mathbf{k})$ for the run with $\Omega = 8$. Darker regions indicate larger energy density. The dashed curve indicates the dispersion relation for inertial waves. (Top left) Normalized $E_{11}(k_x = 0, k_y = 0, k_z, \omega)$. (Top right) Normalized $E_{11}(k_x = 0, k_y = 1, k_z, \omega)$. (Bottom left) Normalized $E_{11}(k_x = 0, k_y = 5, k_z, \omega)$. (Bottom right) Normalized $E_{11}(k_x = 0, k_y = 10, k_z, \omega)$. Note from the maximum values in the color bars how the modes close to the dispersion relation concentrate most of the energy in the first two cases ($k_y = 0$ and $k_y = 1$), while as k_y is increased energy becomes more spread.



Yarom & Sharon, Nature Physics (2014)

If Ω depends on latitude we also have Rossby waves, which are slow traveling waves



These waves are also relevant in accretion disks.

